

Intel(R) Itanium(R) Architecture Assembly Language Reference Guide

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Overview

This document describes the programming conventions used to write an assembly program for the Itanium(R) architecture.

As prerequisites, you should be familiar with the Itanium architecture, and have assembly language programming experience.

About This Document

This document contains the following sections:

- This section lists related documentation and notation conventions.
- Program Elements Overview describes the basic elements and language specifications of an assembly-language program for the Itanium architecture.
- Program Structure describes the directives used to structure the program.
- Declarations describes the directives used to declare symbols in the program.
- Data Allocation describes the statements used to allocate initialized and unitialized space for data objects, and align data objects in the program.
- Miscellaneous Directives describes directives not used to structure a program or to declare symbols.
- Annotations describes the assembler annotations.
- Register Names by Type lists the Itanium architecture registers.
- Pseudo-ops lists the Itanium architecture psuedo operations and their equivalent machine instructions, and pseudo-ops with missing operands.
- Link-relocation Operators lists the link-relocation operators and describes their functionality.
- List of Assembly Language Directives lists the assembly language directives according to category.
- Glossary

Related Documentation

The following documents, available at http://developer.intel.com, rovide additional information:

• Intel(R) Itanium(R) Architecture Software Developer's Manual

Volume 1: Application Architecture, order number 245317-001

Volume 2: System Architecture, order number 245318-001

Volume 3: Instruction Set Reference, order number 245319-001

Volume 4: Itanium Processor Programmer's Guide, order number 245320-001

Software Conventions and Runtime Architecture Guide, order number 245256-002

Notation Conventions

This notation is used in syntax descriptions:

This type	e style	Indicates an element of synta	x a reserved word keyword	, a filename, computer output,
TILES CYPO	. blyic	indicates an element of synta	ix, a reserved word, keyword	, a mename, computer output,

or part of a program example. The text appears in lowercase, unless uppercase is

significant.

This type style Indicates the text you enter as input.

This type style Indicates a placeholder for an identifier, an expression, a string, a symbol or a value.

Substitute one of these items for the placeholder.

[items] Indicates optional items.

[items | item] Indicates the possible choices. A vertical bar (|) separates the items. Choose one of the

items enclosed in brackets.

Program Elements Overview

This section describes the basic elements and language specifications of an assembly-language program for the Itanium (R) architecture. The basic program elements are:

- identifiers
- symbols
- name spaces
- constants
- expressions
- statements.

Identifiers

In Itanium architecture assembly language, objects such as machine instructions, registers, memory locations, sections in the object file, and constants, have symbolic names. In the source code these names are represented syntactically by identifiers.

An identifier may contain letters, digits, and a few special characters. Identifiers may not begin with a digit.

The following table summarizes the rules for character usage in identifiers.

Character Usage in Identifiers

Character Types	First Characters	Remaining Characters
Letters	a-z or A-Z	a-z or A-Z
Special Characters	@ _ \$? .	@ _ \$? .
Digits	not allowed	0-9

The assembler may place a limit on the length of an identifier, but this limit must be no less than 256 characters.

Name Spaces

There are three classes of names in the Itanium architecture assembly language:

- Symbols, which refer to memory locations, sections, and symbolic constants. These names are case sensitive.
- Registers, which refer to registers defined in the Itanium architecture. These names are not case sensitive. Some
 register names consist of multiple syntactic elements rather than a single identifier.
- Mnemonics, which refer to machine instructions, pseudo-ops, directives, and completers. These names are not
 case sensitive.

The assembler places names in three separate name spaces, according to their class. A name may not be defined twice in the same namespace, but it may be defined once in each namespace. When a name is defined in both the register and symbol namespaces, the register name takes precedence over the symbol unless the identifier is "protected" by terminating it with the # operator; this forces the assembler to look up the identifier in the symbol namespace.

The # operator in conjunction with a symbol is legal only when the symbol is an operand.

The following examples illustrate the correct use of the # operator:

r5: //label named r5, where label is the symbol name

movl r4=r5# //;moves the r5 label address to register r4

.global r5# //declares label r5 as global

The # operator is unnecessary and illegal when included in the symbol definition, as shown:

r5#: //illegal

Symbols

A symbol refers to a location in memory, an object file section, a numeric constant, or a register. A symbol has the following attributes:

- name
- type
- value

The special symbols dollar sign (\$) and period (.) when used in expressions, always refer to the current location counter. The current location counter points to the address of a bundle containing the current instruction, or to the address of the first data object defined by the current assembly statement. There is no difference between these symbols, either can be used.

In the following example, the movl instruction moves the address of the bundle containing the current instruction (\$) into register r1:

movl r1=\$

In the following data allocation statement, the period (.) is the address of the first data object defined by the assembly statement:

data4 2, 3, .

Symbol Names

Symbol names are case-sensitive identifiers. Symbols whose names begin with a period (.) are temporary. Temporary symbols are not placed in the object file symbol table. Symbols whose names begin with two periods (..) are temporary, and local. Local symbols are scope restricted symbols. Local symbols are recognized only within the scope in which they are defined. See the Symbol Scope Declaration section for more information about local symbol scopes.

The following table summarizes the rules for using temporary and scope-restricted indicators in different types of symbol names.

Temporary and Scope-restricted Indicators in Symbol Names

Symbol Type	Temporary (.)	Temporary and Scope-Restricted ()
Labels	Allowed	Allowed
Instruction tags	Allowed	Allowed
Function names	Not allowed	Not allowed
Symbolic constants	Not allowed	Not allowed
Section names	Allowed	Not allowed

Symbols whose names begin with an "at" sign (@) are reserved as predefined constants. The assembler provides predefined symbolic constants for special operand values for several instructions, for example, fclass and mux instructions. The following tables list the predefined symbolic constant names for the operands of these instructions. These symbolic constants can be used in expressions as any user-defined symbolic constant.

fclass Condition Predefined Operand Names

Category	fclass Conditions	Predefined Name
NaT test	NaT	@nat
Sign test	Positive Negative	@pos @neg
Class test	Normalized	@norm
	Unnormalized	@unorm
	Signaling NaN	@snan
	Quiet NaN	@qnan
	Zero	@zero
	Infinity	@inf

mux Bytes Operation Predefined Type Operand Names

mux Bytes Operation Type (mbtype)	Predefined Name
Reverse	@rev
Mix	@mix
Shuffle	@shuf
Alternate	@alt
Broadcast	@brcst

Symbol Types

A symbol's type indicates the class of object to which it refers. A symbol type can be any of the following:

label Refers to a location of code or data in memory. A label cannot refer to a procedure

entry point. A code label refers to the address of a bundle. An instruction that follows

a code label always starts a new bundle. The Bundles section provides more

information about instruction bundling.

instruction tag A symbol that refers to an instruction. An instruction tag is used in branch prediction

instructions, and in unwind information directives. Unlike a label, an instruction tag

does not cause the instruction to start a new bundle

function name A symbol that refers to a procedure entry point.

section name Represents an existing section that is active in the output object file.

symbolic constant A constant assigned or equated to a number, symbol, or expression

Symbol Values

A symbol is defined when it is assigned a value. A symbol value can also be a number or expression assigned to a symbolic constant. The value of a symbol identifies the object to which it refers. If the symbol refers to a location in memory, the assigned value is the address of that memory location. In most cases, this address is resolved only in link time.

Register Names

All registers have predefined names, which are listed in Appendix A. Predefined register names are not case-sensitive. You can assign new register names to some of the predefined registers with a register assignment statement, or a rotating register directive. See the Assignment Statements, Equate Statements, and Rotating Register Directives sections, for more details. Registers that use the value of a specified general-purpose register as an index into the register file consist of the register file name followed by the name of a general register enclosed in brackets, such as pmc [r].

The assembler determines the register type according to the form of its name, as shown in the following table. Some registers appear in name and number form. For example, ar.bsp is the name form of an application register, which also has a number form, ar17.

	Register Number and Name	Forms
Register Form	Register Name	Register Type
Number form	r0 - r127	General-purpose 64-bit registers
	in0 - in95	
	10c0 - 10c95	
	out0 - out95	
	f0 - f127	Floating-point registers
	p0 - p63	Predicate registers (1-bit)
	b0 - b7	Branch registers
	ar0 - ar127	Application registers
	cr0 - cr127	Control registers
Name form	e.g. ar.bsp	Named application registers
Name form	0.g. ap	Named application registers
	e.g. cr.dcr	Named control registers
	pr	All-predicate register (64-bits)
	pr.rot	All rotating registers
	ip	Instruction pointer
	psr.l	Processor-status registers
	psr.um	
Indirect file registers	e.g. pmc[r2]	Register file with general-purpose register as index.
User-defined registers	user-name	Registers assigned new names with assignment statements or rotating register directives.

Mnemonics

Mnemonics are predefined assembly-language names for machine instructions, pseudo-ops, directives, and data allocation statements. Mnemonics are not case-sensitive.

Machine Instruction Mnemonics

Machine instruction mnemonics specify the operation to be performed. For example, br is the mnemonic for the branch predict instruction. Some instruction mnemonics include suffixes and optional completers that indicate variations on the basic operation. The suffixes and completers are separated from the basic mnemonic by a period (.). For example, the instructions br.call (branch call), and br.ret (branch return) include suffixes, and are variations of the basic branch (br) instruction.

In this manual, completers are italicized to distinguish them from the instruction mnemonic suffixes. For example, in the instruction brp.ret.sptk.imp b0, L, the optional completers appear in italics to set them apart from the .ret suffix. For a full description of the instructions, see the Intel(R) Itanium(R) Architecture Software Developer's Manual.

Pseudo-op Mnemonics

Pseudo-op mnemonics represent assembler instructions that alias machine instructions. They are equivalent to instruction mnemonics and are provided for the convenience of the programmer. See Pseudo-ops section for a list of the assembler pseudo-ops.

The following is an example of a pseudo-op:

```
mov r5=2
```

The assembler translates this pseudo-op into the equivalent machine instruction:

```
add1 r5=2,r0
```

For more details about the pseudo-ops, see the Intel(R) Itanium(R) Architecture Software Developer's Manual.

Directive Mnemonics

Directives are assembler instructions to the assembler during the assembly process; they do not produce executable code. To distinguish them from other instructions, directive mnemonics begin with a period (.).

The following sections, Program Structure through Annotations, describe the assembler directives and explain how to use them.

Data Allocation Mnemonics

Data allocation mnenonics specify the types of data objects assembled in data allocation statements. See Data Allocation for a list of these mnemonics. Data allocation statements are used to allocate initialized memory areas.

Constants

Constants can be numeric or string.

- Numeric constants contain integers and floating-point numbers.
- String constants contain one or more characters.

Numeric Constants

A numeric constant contains integer and floating-point numbers. The assembler supports C and Microsoft Macro Assembly language (MASM) numeric constants. C numeric constants are the default.

C Numeric Constants

C numeric constants can be any of the following:

- **Decimal integer constants** (base 10) consist of one or more digits, 0 through 9, where 0 cannot be used as the first digit.
- Binary constants (base 2) begin with a 0b or 0B prefix, followed by one or more binary digits (0, 1).
- Octal constants (base 8) consist of one or more digits 0 through 7, where the first digit is 0.
- **Hexadecimal constants** (base 16) begin with a 0x or 0X prefix, followed by a hexadecimal number represented by a combination of digits 0 through 9, and characters A through F.
- Floating-point constants consist of:
- an optional sign or +
- an integer part a combination of digits 0 through 9
- a period .
- a fractional part a sequence of digits 0 through 9
- an optional exponent e or E, followed by an optionally signed sequence of one or more digits

For example, the following floating-point constant contains both the optional and required parts: +1.15e-12.

The following floating-point constant contains only the required parts: 1.0

The following formal grammar summarizes the rules for the C numeric constants:

```
C-constant:
 C-integer-constant
 floating-point-constant
 character-constant
C-integer-constant:
  [1-9][0-9]*
  0[bB][01]*
  0[0-7]*
  0[xX][0-9a-fA-F]*
floating-point-constant:
 integer-part.[ fractional-part ] [ exponent-part ]
integer-part:
  [0-9]*
fractional-part:
  [0-91*
exponent-part:
  [eE][+-][0-9]*
  [eE][0-9]*
```

MASM Numeric Constants

MASM numeric constants can be any of following:

Radix constants are numeric constants that also specify the radix of the value. They consist of one or more digits,
0 through 9, followed by a radix indicator. The radix indicators of MASM numeric constants define them as decimal
(D), hexadecimal (H), octal (O), or binary (B). If the current radix is hexadecimal, the letters B and D are interpreted
as digits. In this case, T specifies a decimal radix, and Y specifies a binary radix. See MASM Radix Indicators table
below.

Radix indicators are not case-sensitive.

See the Radix Indicator Directive section for more information about how to specify a radix.

- Integer constants in the current radix consist of one or more digits, 0 through 9, A through F. If the current radix is not hexadecimal, the characters A through F are not applicable.
- Floating-point constants have the same syntax as in C. See the C Numeric Constants section.

MASM Radix Indicators

The following formal grammar summarizes the rules for the MASM numeric constants:

```
MASM-constant:
    MASM-integer-constant
MASM-radix-constant
floating-point-constant
character-constant

MASM-integer-constant:
    [0-9][0-9a-fA-F]*
MASM-radix-constant
    [0-9][0-9a-fA-F]*[tTdDhHOoqQbByY]
floating-point-constant: (as in C)
```

Characters in Numeric Constants

An underscore (_) can be inserted in a numeric constant to improve readability, as follows 1_000_000. An underscore can be inserted anywhere except before the first character. The assembler ignores underscores.

Characters can represent numeric constants. For instance, a single ASCII character can represent a numeric constant by enclosing it in single quotes (''). The numeric constant is the ASCII value of the specified characterise use other special characters to represent numeric constants, use the character escapes defined in the ANSI C language, and enclose them in single quotes. Table below lists the common character escapes. To use the single quote ('') to represent a numeric constant, insert a backslash (\) before it, and enclose both in single quotes (''), as such, '\'.

Common Character Escapes			
Escape Character	Definition	ASCII Value	
\'	Single quote	39	
\"	Double quote	34	
\b	Backspace	8	
\t	Tab	9	
\n	New line	10	
\f	Form feed	12	
\r	Carriage return	13	
\\	Backslash	92	
\num	Character with octal value num (maximum three digits)	-	
\Xhh	Character with the hexadecimal value hh (maximum two digits)	-	

String Constants

String constants consist of a sequence of characters enclosed in double guotes ("").

To specify double-quotes (") in a string constant, insert a backslash (\) before it, as such, "\"".

To include other special characters in a string constant, use the character escapes defined in the ANSI C language. See table Common Character Escapes for a list of common character escapes.

Expressions

An expression is a combination of symbols, numeric constants, and operators that uses standard arithmetic notation to yield a result. Expressions can be absolute or relocatable.

Absolute Expressions

An expression is absolute when it is not subject to link-time relocation. An absolute expression may contain relocatable symbols, but they must reduce to pairs of the form (R 1 -R 2), where R 1 and R 2 are relocatable symbols defined in the same section in the current source file.

Relocatable Expressions

An expression is relocatable when it is subject to link-time relocation. A relocatable expression contains a relocatable symbol, and may contain an absolute expression. If a relocatable expression contains an absolute expression, it must be reducible to the form (R+K), where R is either a relocatable symbol defined in the current source file, or an undefined symbol, and K is an absolute expression. The address of the relocatable symbol is defined in link time.

Operators

The assembly operators indicate arithmetic or bitwise-logic calculations. Parentheses (()) determine the order in which calculations occur. The assembler evaluates all operators of the same precedence from left to right.

The assembler evaluates all operators according to their level of precedence. Table below lists the operator precedence rules from lowest to highest.

Precedence of Arithmetic and Bitwise Logic Operations		
Precedence 0 (Low)	Operator Symbol +	Operation Addition
	-	Subtraction
	1	Bitwise inclusive OR
1 (Medium)	*	Bitwise exclusive OR Multiplication
	1	Division
	%	Remainder
	<<	Shift Left
	>>	Arithmetic shift right
2 (High)	& -	Bitwise A ND Unary negation
	~	Unary one's complement

Link-relocation Operators

Link-relocation operators generate link-relocation entries in expressions. See Link-relocation Operators for a list of the link-relocation operators.

Statements

An assembly-language program consists of a series of statements separated by a semicolon (;). Multiple statements may be on the same line.

To separate lines, use the standard line termination convention on the local host system, typically CR (carriage return) and LF (line feed). To separate elements within a statement, use the FF (form feed), VT (vertical tab), Space, or Tab that represent white space.

Comments are introduced by the sequence "//" and continue to the end of the line. Comments are ignored by the assembler.

The assembler may place a limit on the length of an input line, but this limit must be no less than 256 characters.

The types of assembly-language statements are as follows:

- · label statements
- · instruction statements
- directive statements
- assignment statements
- equate statements
- data allocation statements
- cross-section data allocation statements

The topics that follow detail each of the statement types, their components and syntax, and provide an example of each.

Label Statements

A label statement has the following syntax:

[label]: // comments

Where:

label

Defines a symbol whose value is the address of the current location counter. If the assembler inserts padding to align the location counter to an implied alignment boundary, the value of the label is not affected.

The assembler interprets a label followed by a double colon (::) as a global symbol. See the Symbol Scope Declaration section for more information about global symbols.

The following is an example of a global label statement:

foo::

Instruction Statements

An instruction statement has the following syntax:

[label:] [[tag:]] [(qp)] mnemonic[.completers] dests=sources //comments

Where:

[tag]

label Defines a symbol whose value is the address of a bundle. When a label is present,

the assembler always starts a new bundle.

If the assembler inserts padding to align the location counter to a bundle boundary,

the label is assigned the address of the newly-aligned bundle.

The assembler interprets a label followed by a double colon (::) as a global symbol.

See Symbol Scope Declaration for more information about global symbols.

Defines a symbol whose value is the bundle address and slot number of the current

instruction.

(qp) Represents a predicate register symbol, which must be enclosed in parentheses. If

this field is not defined, predicate register 0 (p0) is the default.

mnemonic.completers Represents the instruction mnemonic or pseudo-op. Instructions may optionally

include one or more completers. Completers must appear in the specified order in

the instruction syntax.

Mnemonics and completer mnemonics are not case-sensitive.

Refer to the Intel(R) Itanium(R) Architecture Software Developer's Manual for a

description of the machine instructions, pseudo-ops, and completers.

dests =sources Represents the destination and source operands. The operands are register names, expressions, or keywords, depending on the instruction. Some instructions can have

two destination operands, and one or more source operands. When there are multiple operands they are separated by a comma (,). In cases where all operands are destination operands or all operands are source operands, the equal (=) sign is

omitted.

The following is an example of an instruction statement with a label and

```
(db):
```

```
L5: (p7) addl r14 = @gprel(L0), r1
```

The following is an example of an instruction statement with a tag:

```
[t1:] fclass.m.unc p4, p5 = f6, @pos
```

@pos is a predefined constant representing the fclass operation. p4 is true if £6 is positive.

Directive Statements

A directive statement has the following syntax:

.directive [operands] // comments

Where:

. directive Represents the directive mnemonic. Directives always begin with a period (.). Directive

mnemonics are not case-sensitive.

operands The operands are optional and determined by the directive. Where multiple operands are

present in directives, separate them with commas.

The following is an example of a directive statement:

.proc foo

Assignment Statements

Assignment statements enable the programmer to define or redefine a symbol by assigning it a value. This value may be a reference to another symbol, register name, or expression. The new value takes effect immediately and remains in effect until the symbol is redefined. Symbols defined in assignment statements do not have forward references.

In addition, symbols defined in assignment statements cannot:

- appear in the symbol table of an output object file.
- be declared global.
- be defined in an equate statement.

There are two types of assignment statements:

- Symbol assignment statements, which define or redefine a symbol in the symbol name space.
- Register assignment statements, which define or redefine a register name in the symbol name space.

Symbol Assignment Statements

A symbol assignment statement has the following syntax:

identifier=expression // comments

Where:

identifier Represents a symbol in the symbol name space.

expression Specifies the type and value of the identifier. The expression cannot contain forward

references.

The following is an example of an assignment statement that defines a symbol:

C = L0+2

Register Assignment Statements

A register assignment statement has the following syntax:

identifier=register name // comments

Where:

identifier Represents a register name in the symbol name space.

register name Specifies an alternate register name. If the register name is a stack or rotating register

name, the new register name continues to reference the previously-defined register name, even if the name is no longer in effect. See the Register Stack Directive and Rotating

Register Directives sections.

The following is an example of an assignment statement that defines a register name:

A = r1

Equate Statements

Equate statements enable the programmer to define a symbol by assigning it a value. This value may be a reference to another symbol, register name, or expression. In equate statements, a symbol can be defined only once throughout the source file. These symbols may have forward references, except when referencing a register name. A symbol name defined in an equate statement cannot be defined in an assignment statement.

Equate statements have the same syntax as assignment statements, except for the operator.

There are two types of equate statements:

- · symbol equate statements
- register equate statements

Symbol Equate Statements

A symbol equate statement has the following syntax:

identifier==expression // comments

Where:

identifier Represents a symbol in the symbol name space.

expression Specifies the type and value of the identifier. The expression can contain forward references.

The following is an example of an equate statement that defines a symbol:

A == 5

Register Equate Statements

A register equate statement has the following syntax:

identifier==register name // comments

Where:

identifier Represents a register name in the symbol name space.

register name Specifies an alternate register name. The register name cannot contain forward references. If the

register name is a stack or rotating register name, the new register name continues to refer to the previously-defined register, even if the name is no longer in effect. See the Register Stack

Directive and Rotating Register Directives sections.

The following is an example of an equate statement that defines a register name:

A == r1

Data Allocation Statements

A data allocation statement has the following syntax:

[label:] dataop operands // comments

Where:

label Defines a symbol whose value is the address of the first data object defined by the statement. If the

assembler inserts padding to align the location counter to an implied alignment boundary, the label

is assigned the value of the newly-aligned address.

The assembler interprets a label followed by a double-colon (::) as a global symbol. See the

Symbol Scope Declaration section for more information about global symbols.

dataop Defines the type and size of data objects that are assembled. Data object mnemonics are not case-

sensitive. The Data Allocation Statements section lists the data object mnemonics.

operands Contain multiple expressions separated by commas. Each expression defines a separate data

object of the same type and size. The assembler puts the data objects into consecutive locations in

memory, and automatically aligns each to its natural boundary.

The following is an example of a data-allocation statement with a label:

L2: data4.ua L1, L1+7, .t1+0x34, \$-15

Cross-section Data Allocation Statements

A cross-section data allocation statement has the following syntax:

xdataop section-name, operands //comments

Where:

xdataop Defines the type and size of data objects that are assembled. Cross-section data object

mnemonics are not case-sensitive.

section-name Refers to a predefined name of an existing section in the object file.

operands Contain multiple expressions that are separated by commas. Each expression defines a

separate data object of the same type and size. The assembler puts the data objects into consecutive locations in memory, and automatically aligns each to its natural boundary.

The following is an example of a cross-section data allocation statement:

.xdata8 .data, 0x123, L1

Program Structure

This section describes the Itanium(R) architecture assembly language directives associated with symbol declarations. These directives can be used to perform the following functions:

- Declare symbol scopes
- Specify symbol types
- Specify symbol sizes
- Override default file names
- Declare common symbols
- Declare aliases for labels, function names, symbolic constants, or sections

Sections

The output object file of an assembly program is made up of named sections that contain code and data. The assembler allows any number of sections to be created in parallel within the output object file, one of which can be accessed at a time. The section currently accessed is referred to as the current section.

The assembler maintains a separate location counter for each existing section. The assembler always adds new code or data to the end of the current section, moving the location counter in that section ahead to incorporate the new code or data. The Cross-section Data Allocation Statements section explains how to add data to a section that is not the current section.

Section directives and predefined section directives are used to define and switch between sections. Some section directives have flag and type operands that specify the flag and type attributes of a section.

Section Flags and Section Type Operands

The flags operand specifies one or more flag attributes of a section. The flags operand is a string constant composed of one or more characters. Table Section Flag Characters lists the valid flag characters. The flags operand is casesensitive. The assembler does not detect invalid specifications made by the programmer, such as stores to a section that is a non-writable section. A non-writable section is not flagged by the w flag character.

Section Flag Characters		
Flag Characters	Description	
W	Write access allowed.	
a	Section is allocated in memory.	
X	Section contains executable instructions.	
S	Section contains "short" data.	
0	Section adds ordering requirement.	
	The 'o' flag is only for ELF (Unix) files.	

The type operand specifies a section's type attribute. The type operand is a string constant containing one of the valid section types listed in Table Section Types. The section types listed in the table correspond directly to ELF (UNIX*) section types, except for the "comdat" section type, which corresponds to COFF32 (Windows NT). The type operand is case-sensitive.

Section Types	
Section Type	Description
"progbits"	Sections with initialized data or code.
"nobits"	Sections with uninitialized data (bss).
"comdat"	COMDAT sections, Windows NT
	specific. See Windows NT (COFF32) Specific Section Flag Operands.
"note"	Note sections.

Windows NT (COFF32) Specific Section Flag Operands

In addition to the section flags described in Section Flags and Section Type Operands, the assembler recognizes the flags listed in table COMDAT Section Flag Characters (below) when the section type is "comdat" and the object file format is COFF32 (Windows NT).

These flags represent link-time selection criteria, and are case-sensitive.

COMDAT Section Flag Characters	
Flag	Description
D	Allow only one instance of this section.
Y	Select any one instance of this section.
Е	Select any one instance of this section; all instances must have identical contents.
L	Select the largest instance of this section.
A	Select an instance of this section only if the associated section name is selected. See <u>Associated Section Name Flag</u> section that follows.

Associated Section Name Flag

When the A flag is present, the assembler identifies an associated section name. Use the A flag in conjunction with an associated section operand.

The associated section operand is a section name. A section name can only be loaded in link time if the associated section is already loaded.

To select the \mathbb{A} flag, use the .section or .pushsection directive with an additional assoc-section operand in one of the following formats:

Where:

section-name	Represents a user-defined name using any valid identifier. Section names are case- sensitive.
flags	Represents a string constant composed of one or more characters that specify the attributes of a section. See table Section Flag Characters for a list of the valid flag characters.
type	Represents a string constant specifying a type attribute of a section. See table Section Types for a list of the section types
assoc-section	Represents a user-defined section name.

Section Definition Directive

The .section directive defines new sections, switches from one section to another, and sets the current section.

The .section directive has the

following formats, with a different functionality for each format:

.section section-name

.section section-name,"flags","type"

.section section-name = "flags","type"

Where:

section-name	Represents a user-defined name using any valid	
	identifier. Section names are case-sensitive.	
flags	Represents a string constant composed of one or more	
	characters that specify the attributes of a section. See	
	Table Section Flag Characters for a list of the valid flag characters.	
type	Represents a string constant specifying a type attribute	
	of a section. See Table Section Types for a list of the section types.	

In the first format, the .section directive sets the section-name as the current section. In the second format, the .section directive defines a new section, assigns flags and type attributes, and makes the newly-defined section the current section. If the newly-defined section has the same name, flag attributes, and type attribute as a previously-defined existing section, the assembler switches to the previously-defined section without defining a new one. For example, the following .section directive defines a new section (my_section), assigns flags ("aw") and type ("progbits") attributes, and makes it the current section.

```
.section my section, "aw", "progbits"
```

In the third format, the .section directive creates a new section with a previously-defined section name, and assigns it new flags and type attributes. The newly-created section becomes the current section; any reference to this section name refers to the newly-created section. The Using Section Directives section illustrates how to use the .section directive.

Section Return Directive

The .previous directive returns to the previously-defined section of the current section and makes it the current section. This directive does not affect the section stack. The Using Section Directives section illustrates how to use this directive.

Absolute Sections

Absolute sections are only supported by ELF object file formats. To define an absolute section with a fixed starting address, use the .section and .pushssection directives with an optional origin operand. The origin operand must be an absolute expression. Absolute section addresses cannot overlap. The linker does not merge absolute sections with other section types, or with other absolute sections.

The following example defines a new section name and assigns it new flags and type attributes, with a starting address specified by the origin parameter.

```
.section new name, "aw", "progbits", 0x1000
```

Section Stack Directives

The assembler maintains a section stack, which is defined by the .pushsection and .popsection directives. These directives push and pop previously-defined sections to and from the section stack. The assembler may limit the depth of a section stack, but it must allow at least ten levels. The .pushsection directive pushes the current section onto the stack and switches to the section specified in the directive. The .pushsection directive, like the .section directive, has one of the following formats:

```
.pushsection section-name
```

- .pushsection section-name, "flags", "type"
- .pushsection section-name = "flags", "type"

Where:

section-name	Represents a user-defined name using any valid identifier. Section names are case-sensitive.
flags	Represents a string constant composed of one or more characters that specify the attributes of a section. See table Section Flag Characters for a list of the valid flag characters.
type	Represents a string constant specifying a type attribute of a section. See table SectionTypes for a list of the section types The .popsection directive pops the previously-pushed section from the top of the stack, and makes it the current one.

The Using Section Directives section illustrates how to use the .pushsection and .popsection directives.

Predefined Section Directives

The predefined section directives define and switch between commonly-used sections. A predefined section directive creates a new section with the default flags and type attributes, and makes that section the current section.

The predefined section directive mnemonics are the same as the section names. The assembler generates section names in lower case, even though directive mnemonics are not case-sensitive.

On some platforms the assembler automatically creates a local symbol with a "section" type attribute for each defined section in the object file. See the Symbol Type Directive section for more information about symbol types.

The linker combines sections with the same name, flags and type attributes. The linker creates two separate output sections for sections with the same name, but different flags and type attributes.

To define a section without the default flags and type attributes, use the .section directive.

The predefined section directives cannot define a new section using the same name as a previously-defined section.

Table <u>Predefined Section Directives</u> below lists the predefined section directives, and their default flags and type attributes. A predefined section directive can have the same name as a section name.

Predefined Section Directives			
Directive/Section Name	Flags	Туре	Usage
.text	"ax"	"progbits"	Read-only object code.
.data	"wa"	"progbits"	Read-write initialized long data.
.sdata	"was"	"progbits"	Read-write initialized short data.
.bss	"wa"	"nobits"	Read-write uninitialized long data.
.sbss	"was"	"nobits"	Read-write uninitialized short data.
.rodata	"a"	"progbits"	Read-only long data (literals). ELF (Unix) format only.
.comment	" "	"progbits"	Comments in the object file. ELF format, and COFF format only when used with the -Q y command-line option.

Sections Linking Directive

The .seclink directive declares a link between one section to another section. This directive can be used to link an unwind information section with the user-defined executable section.

The .seclink directive has the following syntax:

```
.seclink section-name, linked-to-section-name
```

Where

section-name	Represents the name of a section that links to another section.	
link-to-section-name	Represents the name of a section the section-name links to.	

Using Section Directives

The following code illustrates the use and behavior of the section directives .text, .section, .pushsection, .popsection, and .previous:

```
Example: Code Sequence Using Section Directives
                       //Default
.text
.section A
             //Makes A the current section.
         //.text is A's previous section.
.pushsection B //Pushes A onto the stack and makes B the
         //current section. A is B's previous section.
.pushsection C //Pushes B onto stack and makes C the current
         //section, B is C's previous section.
.popsection
              //Pops B from stack and makes it current.
              //Pops A from stack and makes it current.
.popsection
         //.text is A's previous section.
             //Makes A's previously current section .text the
.previous
         //current section. A becomes .text's previous
         //section.
.previous
             //Makes A the current section, .text becomes A's
         //previous section.
```

Include File Directive

To include the content of another file in the current file, use the .include directive (see Preprocessor Support) or use the #include directive of the standard C preprocessor.

To include the contents of another file in the current source file, use the .include directive in the following format:

.include "filename"

Where:

"filename"	Specifies a string constant. If the specified filename is an absolute pathname, the file is included. If the		
	specified filename is a relative pathname, the assembler performs a platform-dependent search to locate the include file.		

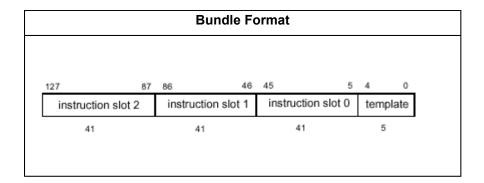
Bundles

Itanium architecture instructions are grouped together in 128-bit aligned containers called bundles. Each bundle contains three 41-bit instruction

slots, and a 5-bit template field. The template field specifies which type of execution unit processes each instruction in the bundle. Bit 0 is set to 1 if

there is a stop at the end of a bundle. There is no fixed relation between the boundaries of an instruction group and the boundaries of a bundle.

Figure below illustrates the format of a bundle.



Multiway branch bundles contain more than one branch instruction. When the first branch instruction of a multiway bundle is taken, the subsequent branch instruction does not execute.

Bundles are always aligned at 16-byte boundaries. The assembler automatically aligns sections containing bundles to at least 16-bytes.

Bundling can be:

- implicit (automatically performed by the assembler)
- explicit (specified by the programmer)
- with automatic selection of the template
- with explicit selection of the template

Refer to the Intel(R) Itanium(R) Architecture Software Developer's Manual for more details about bundles.

Implicit Bundling

The assembler bundles instructions automatically by default.

In the implicit-bundling mode, section directives do not terminate a partially-filled bundle of a previously-defined section. This means that the assembler can return to the previous section and continue to fill the bundle.

In implicit-bundling mode, a label forces the assembler to start a new bundle.

Explicit Bundling

The programmer can explicitly assemble bundles by grouping together up to three instructions, and enclosing them in braces ({}). The assembler

places these instructions in one bundle, separate from all preceding and subsequent instructions. Stops at the end of an explicit bundle can be

placed before or after the closing brace.

Section directives and data allocation statements cannot be used within an explicit bundle. Cross-section data allocation statements can be used

within an explicit bundle. See the Cross-section Data Allocation Statements section for more information.

In explicit-bundling mode, labels can be inserted only as the first statement of an explicit bundle. Instruction tags can be applied to any instruction.

When using explicit-bundling, the appropriate template can be selected in one of the following ways:

- automatically by the assembler.
- explicitly by the programmer, using the explicit-template directives.

Auto-template Selection

By default, the assembler searches and selects a matching template for a bundle. The template fields specify intra-bundle instruction stops. When

two templates consist of the same sequence of instruction types, they are distinguished by stops. The assembler selects the appropriate template

field based on the stops within the bundle. If no template is found, the assembler produces a diagnostic message. Instruction group stops mayoccur in a bundle.

Explicit Template Selection

To explicitly select a specific template, use one of the directives listed in table <u>Explicit Template Selection Directive</u> (below) as the first statement of your code within the braces. For example, the <code>.mii</code> directive selects the memory-integer-integer (mii) template.

Explicit Template Selection Directives

Directive		Templa	Template Selection		
	Slot 0	Slot 1	Slot 2		
.mmi	memory	integer	integer		
.mfi	memory	floating point	integer		
.bbb	branch	branch	branch		
.mlx	memory	long immediate			
.mib	memory	integer	branch		
.mmb	memory	memory	branch		
.mmi	memory	memory	integer		
.mbb	memory	branch	branch		
.mfb	memory	floating point	branch		
.mmf	memory	memory	floating point		

Refer to the Intel(R) Itanium(R) Architecture Software Developer's Manual for more information about template field encoding and instruction slot

mapping.



Select the .mlx directive for the move long immediate instruction and for the long branch instruction. These instructions operate on 64-bit data types and are too large to fit into one of the 41-bit bundle slots. This directive selects the mlx template and inserts the instruction in slot 1 and slot 2 of the bundle.

Example below is the code that shows an explicit bundle using explicit template selection, and a stop.

Instruction Groups

Itanium architecture instructions are organized in instruction groups. Each instruction group contains one or more statically contiguous instruction(s) that can execute in parallel. An instruction group must contain at least one instruction; there is no upper limit on the number of instructions in an instruction group.

An instruction group is terminated statically by a stop, and dynamically by taken branches. Stops are represented by a double semi-colon (;;). The programmer can explicitly define stops. Stops immediately follow an instruction, or appear on a separate line. They can be inserted between two instructions on the same line.

Refer to the Intel(R) Itanium(R) Architecture Software Developer's Manual for more detailed information about instruction groups.

Dependency Violations and Assembly Modes

Dependency violations occur when instructions within an instruction group access the same resource register, including registers that appear as implicit operands. Dependency violations result in architecturally undefined behavior. The assembler can detect and eliminate dependency violations that occur within instruction groups, depending on its mode.

The assembler reads and processes assembly code in one of two modes: explicit and automatic.

Use explicit mode if you are an expert user with profound knowledge of tanium architecture or performance is important. In explicit mode, you are responsible for bundling and stops (;;), and the assembler generates errors where it finds dependency violations.

Use automatic mode if you are a novice user or performance is not the highest consideration. In automatic mode, the assembler bundles the code and adds stops to avoid dependency violations. It ignores existing stops and annotations.

You can mix code from both modes in the one file. Set the mode using the command-line option or the directives .auto and .explicit. The directive .default causes the assembler to revert to the mode of operation defined in the command line.

For a complete description of the rules of data dependencies, see the *Intel(R) Itanium(R) Architecture Software Developer's Manual*.

This feature may not be currently supported by all assemblers.

Procedures

Software conventions require that instructions belong to a declared procedure, and that procedure prologues be separated from the main body within the procedure. These conventions ensure that the proper stack unwind information is placed in the object file. Refer to the *Software Conventions and Runtime Architecture Guide* for details about the software conventions.

Procedure Directives

The .proc and .endp directives combine code belonging to the same procedure. The .proc directive marks the beginning of a procedure, and the .endp directive marks the end of a procedure. A single procedure may consist of several disjointed blocks of code. Each block should be individually bracketed with these directives. Name operands within a procedure can be used only for that specific procedure.

The .proc directive declares a symbol as a function. The .proc directive does not define the symbol by assigning it a value. Symbols must be defined as a label within the procedure. When name is defined, it is automatically assigned a "function" type.

The following code sequence shows the basic format of a procedure:

Where:

name	Represents one or more entry points of the procedure. Each entry point has a different name. The assembler ignores the
	name operands of the .endp directive.

Procedure Label (PLabel)

When the object file format is COFF32 (Windows NT), the assembler creates two symbols for a defined procedure. One symbol represents the procedure entry point and appears in the object file symbol table with the original symbol name preceded by a dot. For example, the label named $f \circ \circ$ becomes $f \circ \circ$ in the object file symbol table. The other symbol represents the procedure label, also referred to as the function descriptor or PLabel, and is implicitly generated by the assembler using the original symbol name. Refer to the *Software Conventions and Runtime Architecture Guide* for more information about the procedure label.

Stack Unwind Directives

Stack unwind directives are used to generate unwind information for a procedure.

The Software Conventions and Runtime Architecture Guide describes stack unwind elements and their semantics. Refer to this document for information about the semantics of the stack unwind directives described in this section.

Procedures Used for Stack Unwind Directives

Procedures are bound by the <code>.proc</code> and <code>.endp</code> directives. See the Procedure Directives section for more information about these directives. Procedures are section-sensitive. The assembler interprets stack unwind directives according to the procedure in which they appear.

Procedures contain prologue and body regions that are divided by headers. These headers are specified using the .prologue and .body directives.

The .prologue directive introduces a prologue region within a procedure. Each prologue region must be introduced by the .prologue directive.

The .body directive separates the procedure prologue from the main body of the procedure. You can use the .body directive more than once within procedures with multiple body regions.

For language specific data, use the .handlerdata directive followed by handler data allocations with the .endp directive after the handler data allocations. The assembler places the handler data in the .xdata section.

See the Stack Unwind Directives Usage Guidelines section for more information about using this directive.

These directives may not be currently supported by all assemblers.

Example: Procedure Format in a Code Sequence

.handlerdata //data allocations go to .xdata section

.endp name,... //end of procedure

Example below, <u>Procedure Format in a Code Sequence</u>, illustrates the format of a procedure with two prologues, two body regions, and language specific data.

.proc name,... //start of procedure .prologue //instructions in first prologue .body //instructions in first body region .prologue //instructions in second prologue .body //instructions in second body region

List of Stack Unwind Directives

Stack unwind directives, except for the <code>endp</code> directive, do not break bundles. When a tag operand is present in a stack unwind directive, the tag refers to a location of an instruction slot. If the tag is omitted, the location default is the location counter of the next instruction. More than one directive can refer to the same location of an instruction slot.

Generally, functions have unwind table entries. A stack unwind directive must be present between the .proc and .endp directives to write function entries and unwind information to the unwind table.

To create a function entry for unwind information when there is no stack unwind information, use the .unwentry directive.

The table that follows, Stack Unwind Directives, lists the stack unwind directives and their operands. The right-most column of the table summarizes the records and fields that are affected by these directives. For more information about the affected records and fields, refer to the *Software Conventions and Runtime Architecture Guide*.

Stack Unwind Directives				
Directive Name	First Operand	Second Operand	Third Operand	Affected Records and Fields
.proc	symbol			entry-start
.endp				entry-end
.handlerdata				handler data allocation
.unwentry				entry generation
.prologue				prologue header previous header
.prologue	imm-mask	grsave		prologue header previous header
.body				body header
				previous header
.personality	symbol	[phases]		personality
.fframe	size	[tag]		mem_stack_f
.vframe	gr-location	[tag]		mem_stack_v
				psp_gr
.vframesp	spoff	[tag]		mem_stack_v
				psp sprel
.vframepsp	pspoff	[tag]		mem_stak_v
				pso_psprel
.restore	sp	[ecount]	[tag]	epilogue
.copy_state	state_no			copy_state
.label_state	state_no			label_state
.save	rp	gr-location	[tag]	rp_when
				rp_gr
.altrp	br-location			rp_br
.savesp rp	rp	imm-location	[tag]	rp_when
				rp_sprel
.savepsp rp	rp	imm-location	[tag]	rp_when
				rp_psprel

.save	ar.fpsr	gr_location	[tag]	fpsr_when
				60.00
				fpsr_gr
.savesp	ar.fpsr	imm_location	[tag]	fpsr_when
				fpsr_sprel
.savepsp	ar.fpsr	imm_location	[tag]	fpsr_when
				fpsr_psprel
.save	ar.bsp	gr_location	[tag]	bsp_when
				bsp gr
.savesp	ar.bsp	imm_location	[tag]	bsp_when
				bsp sprel
.savepsp	ar.bsp	imm location	[tag]	bsp_when
.save	ar.bsp	gr location	[tag]	bsp_psprel bspstore when
. save	ar.bsp	gi_iocation	[cag]	bspscore_witen
	store			bspstore_gr
.savesp	ar.bsp	imm_location	[tag]	bspstore_when
	store			bspstore_sprel
.savepsp	ar.bsp	imm_location	[tag]	bspstore_when
	store			bspstore_psprel
.save	ar.rnat	gr_location	[tag]	rnat_when
				rnat gr
.savesp	ar.rnat	imm_location	[tag]	rnat_when
				rnat sprel
.savepsp	ar.rnat	imm_location	[tag]	rnat_when
		_	_	
.save	ar.pfs	gr-location	[tag]	rnat_psprel pfs_when
	G1.b10	griodation	[[[[]]	P-10
				pfs_gr
.savesp	ar.pfs	imm-location	[tag]	pfs_when
				pfs_sprel
.savepsp	ar.pfs	imm-location	[tag]	pfs_when
				pfs_psprel
.save	ar.unat	gr-location	[tag]	natcr_when
				natcr gr
.savesp	ar.unat	imm-location	[tag]	natcr_when
				nator enrol
.savepsp	ar.unat	imm-location	[tag]	natcr_sprel natcr when
				_
9776	ar.lc	gr-location	[tag]	natcr_psprel lc when
.save	ar.ic	gr-10cal1011	[Lay]	TC_wileii

				lc_gr
.savesp	ar.lc	imm-location	[tag]	lc_when
				lc_sprel
.savepsp	ar.lc	imm-location	[tag]	lc_when
				lc_psprel
.save	pr	gr-location	[tag]	preds_when
				preds_gr
.savesp	pr	imm-location	[tag]	preds_when
				preds sprel
.savepsp	pr	imm-location	[tag]	preds when
			[[[]]	F
				preds_psprel
.save	@priunat	gr_location	[tag]	priunat_when
				priunat_gr
.savesp	@priunat	imm_location	[tag]	priunat_when
				priunat sprel
.savepsp	@priunat	imm location	[tag]	priunat when
				_
	<u> </u>			priunat_psprel
.save.g	imm-grmask	7	F / 1	gr_mem spill_imask
.save.g	imm_grmask	gr_location	[tag]	gr_gr imask
.save.f	imm-frmask			fr_mem
				spill_imask
.save.b	imm-brmask			br_mem
				spill imask
.save.gf	imm-grmask	imm-frmask		frgr_mem
.save.b	imm-brmask	gr-location		spill_imask br gr
. 54 v C . 5	Thun Dimagn	griccation		\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\
				spill_imask
.spill	imm- location			spill_base
.spillreg	reg	treg	[tag]	spill reg
.restorereg		reg	[tag]	spill_reg
.spillsp	reg	imm_location	[tag]	spill_sprel
.spillpsp	reg	imm_location	[tag]	spill_psprel
.spillreg.p ¹	qp qp	reg	treg	spill_reg_p
.restorereg.p	qp	reg	[tag]	spill_reg_p
.spillsp.p	qp	reg	imm_location	spill_sprel_p
.spillpsp.p	qp	reg	imm_location	spill_psprel_p
·25111525.5				

Stack Unwind Directives Operands

The following alphabetical list defines the stack unwind directive operands listed in the table Stack Unwind Directives:

- ar.pfs, ar.unat, and ar.lc are explicit register names.
- br-location is the alternative branch register used to get the return link. By default, b0 is the return link.
- ecount is the number of prologues -1 specified by the assembler if this field is not specified by the user.
- gr-location is a general-purpose register that specifies the destination of the save operation. For example, registers r1 and loc1.
- grsave saves the rp, ar.pfs, psp, and pr register contents to the first general-purpose register.
- imm-location (immediate location) is the offset between the sp or psp, and the <code>save_address</code>, specified in bytes. This offset is always positive and specified as follows:
- imm-mask (immediate mask) is an integer constant specifying a bit pattern for the preserved registers, as follows:
- The immediate mask (imm-mask) of the .prologue directive is specified as follows: rp (return link) (bit 3), ar.pfs register (bit 2), psp (previous stack pointer) (bit 1), pr register (bit 0)
- The immediate mask (imm-frmask) of the .save.f and .save.gf directives refer to the preserved floating-point registers.
- The immediate mask (imm-grmask) of the .save.g and .save.gf directives refer to the preserved general registers.
- The immediate mask (imm-brmask) of the .save.b directive refers to the preserved branch registers.
 - os-type is one of @svr4, @hpux, or @nt. It specifies the operating system type.
 - phases is the number of phases, ranging from 0 to 3.
 - pr is an explicit register name.
 - @priunat is a predefined symbol and indicates a primary unat.
 - psp is the location of the previous stack frame.
 - psp offset: imm-location = psp address save address. See also imm-mask.
 - qp is one of the following predicate registers: p1-p63.
 - reg is one of the following registers: r4-r7, f2-f5, f16-f31, b1-b5, pr, @psp, @priunat, rp, ar.bsp, ar.bspstore, ar.rnat, ar.unat, ar.fpsr, ar.pfs, or ar.lc.
 - rp is an explicit register name.
 - size is the fixed frame size in bytes.
 - sp is an explicit register name.

- sp offset: imm-location = save address sp address. See also imm-mask.
- state no is the state copied or restored.
- symbol is an assembly label.
- tag is an optional operand, which specifies a "when" attribute of the operation described by the directive.
- treg is one of the following registers: r1-r127, f2-f127, or b0-b7.

Syntax for the .save.x Directives

The directives, .save.f, .save.g, .save.gf, and .save.b, define 2-bit fields for each save operation in the imask descriptor. The assembler

interprets the instruction that immediately follows a save directive as a save instruction.

Example Code Sequence Using the .save.g Directive illustrates the use of the .save.g directive. Each .save.g directive describes the subsequent store instruction. The operand is a mask where only one bit is set. This bit specifies the preserved saved register. The assembler produces a gr_mem descriptor with a 0x5 mask. In addition, the assembler marks the 2-bit fields of the imask descriptor, corresponding to the slots of the two store instructions.

```
Example: Code Sequence Using the .save.g Directive

.save.g 0x1
st8... = r4
...
.save.g 0x4
st8... = r6
```

Example <u>Code Sequence Using the .save.gf Directive</u> illustrates the use of the .save.gf directive. The .save.gf directive describes the subsequent store instruction. The operands is a mask where only one bit is set. This bit specifies the preserved saved register. The assembler produces a frgr_mem descriptor with a 0x42 mask for the floating-point registers and a 0x2 mask for the general-purpose registers. In addition, the assembler marks the 2-bit fields of the imask descriptor, corresponding to the slots of the three store instructions.

```
Example: Code Sequence Using the .save.gf Directive

.save.gf 0, 0x2
fst... = f3
...
.save.gf 0, 0x40
fst... = f18
...
.save.gf 0x2, 0
st8... = r5
```

Stack Unwind Directives Usage Guidelines

Follow these guidelines when using the stack unwind directives:

- Place stack unwind directives between the unwind entry point of the function declared in .proc and .endp.
- The first directive in each region in a procedure must be one of the following region header directives, .prologue or .body.
- The first directive in the procedure must point to the same address as the first unwind entry point of the function.
- No two consecutive prologue regions are allowed.
- When none of the stack unwind directives listed in the Stack Unwind Directives table are specified, optionally use
 the .unwentry directive to create an unwind entry for the function. Do not use this directive if the unwind records
 are filled by the compiler.
- Use tags only within the current region. A tag operand cannot be specified out of the scope region. If a tag is omitted, the directive refers to the next instruction, which resides in the same region.
- Use only one .personality directive at any point within each procedure.
- Always precede the .handlerdata directive with the .personality directive.
- Follow these guidelines for prologue regions:
- Use one of the following frame directives if the procedure creates a new stack frame: .fframe, .vframe, or .vframesp.
- Use each of the .save directives only once. For example: .save rp, ar.pfs, ar.unat, ar.lc, and pr.
- Multiple usage of the directives, .save.g, .save.f, .save.b, and .save.gf is allowed. The number of bits set in the bit-mask operand specifies the number of the consecutive save instructions that immediately follow the directive.
- A single unwind record is built for one or more occurrences of the following directives: .save.g, .save.f, .save.b, and .save.gf. The bit-mask field of the record is a bitwise OR of all the masks that appear in the directives.
- Use only one .save.b with the gr-location operand.
- Use only one .spill directive.
- The .prologue <imm_mask> directive with the psp bit set and the .vframe directive both define the psp location. Use only one of them.
 - Use only one .restore directive for body regions.

Using Stack Unwind Directives Example

The example below is a simple "Hello World" function that shows the usage of local and output registers. For comparison, the first part (A) does not include unwind directives, and the second part (B) includes stak unwind directives and DV detection clues.

Using Unwind Directives

```
A. "Hello World" Function Without Unwind Directives
// The string is defined in the read only data
section
.section .rdata, "a", "progbits"
.align 8
.STRING1:
stringz "Hello World!!!\n"
// The definition of the function hello is in the
text section
// The following registers are saved in local
registers:
    gp = r1 - loc0 = r32
//
//
   rp = b0 - loc1 = r33
     ar.pfs - loc2 = r34
//
   sp = r12 - loc3 = r35
//
.text
.global hello
.proc hello
hello:
alloc loc2 = ar.pfs, 0, 4, 1, 0
mov loc3 = sp
mov loc1 = b0
addl out0 = @ltoff(.STRING1), gp
ld8 out0 = [out0]
mov loc0 = qp
br.call.sptk.many b0 = printf
;;
mov gp = loc0
mov ar.pfs = loc2
mov b0 = loc1
mov sp = loc3
br.ret.sptk.many b0
.endp hello
.global printf
.type printf, @function
```

B. "Hello World" Function With Unwind Directives

```
.file "hello.c"
.pred.safe_across_calls p1-p5,p16-p63

.section .rdata, "a", "progbits"
.align 8
.STRING1:
stringz "Hello World!!!\n"
.text
.align 16
.global hello#
.proc hello#
hello:
.prologue
```

```
.save ar.pfs, r34
alloc r34 = ar.pfs, 0, 4, 1, 0
.vframe r35
mov r35 = r12
.save rp, r33
mov r33 = b0
.body
addl r36 = @ltoff(.STRING1), gp
;;
1d8 r36 = [r36]
mov r32 = r1
br.call.sptk.many b0 = printf#
mov r1 = r32
mov ar.pfs = r34
mov b0 = r33
.restore sp
mov r12 = r35
br.ret.sptk.many b0
.endp hello#
.global printf#
.type printf#, @function
```

Windows NT (COFF32) Symbolic Debug Directives

When the object file format is COFF32 (Windows NT), the symbolic debug directive .ln stores the line number table entry of a function in the symbolic debug information. The symbolic debug directive .ln must be enclosed within a function defined by the .bf and .ef directives. The .bf and .ef directives define the beginning and the end of a function.

The .ln directive has the following format:

.ln line-number[,function]

Where:

line-number	Specifies the source line number associated with the next assembled instruction.
function	Is the name of the current function.

The .bf and .ef directives have the following format:

```
.bf function, line
.ef function, line, code-size
```

function	Represents the function name.
line	Is an integer number corresponding to the first source line of the function.
code-size	Is an integer number representing line group code size, which is written as debug information.

Declarations

This section describes the Itanium(R) architecture assembly language directives associated with symbol declarations. These directives can be used to perform the following functions:

- · Declare symbol scopes
- Specify symbol types
- · Specify symbol sizes
- · Override default file names
- Declare common symbols
- Declare aliases for labels, function names, symbolic constants, or sections

Symbol Scope Declaration

Symbols are declared as global, weak, or local scopes. Symbol scopes are used to resolve symbol references within one object file or between multiple object files. The symbol scope attribute is placed in the object file symbol table and any reference to a symbol is resolved in link time. By default, symbols have a local scope, where they are available only to the current assembly-language source file in which they are defined.

Local Scope Declaration Directive

References to symbols with a local scope are resolved from within the object file in which the symbols are declared. Local symbols with the same name in different object files do not refer to the same entity. Symbols have a local scope by default, so it is not necessary to declare symbols with local scopes. However, the .local directive is available for completeness. The .local directive has the following format:

```
.local name, name, ...
```

name	Represents a symbol name.
Hame	i Nepresents a symbol name.

Global Scope Declaration Directive

References to symbols with a global scope are resolved within the object file in which the symbols are declared, and within other object files. Global symbols with the same name in different object files refer to the same entity.

To declare one or more symbols with a global scope, use the .global directive. These symbols are flagged as global symbols for the linkage editor. The .global directive has the following format:

```
.global name, name, ...

Where:

name Represents a symbol name.
```

Weak Scope Declaration Directive

References to symbols with a weak scope are resolved within the object file in which the symbols are declared, and within other object files. Weak symbols with the same name in different object files may not refer to the same entity. When a symbol name is declared with a weak scope as well as a global or local scope, the global or local scope will take precedence over the weak scope in link time.

To declare one or more symbols with a weak scope, use the .weak directive. These symbols are flagged as weak symbols for the linkage editor. The weak scope declaration format for UNIX* (ELF) and Windows NT (COFF32) differ and are described in the sections that follow.

Weak Scope Declaration for UNIX (ELF)

For UNIX (ELF), use the .weak directive in the following format:

```
weak name1, name2, ...

Where:

name Represents a symbol name.
```

The following example illustrates how to declare an undefined symbol with a weak scope. The defined symbol x: has a local scope. y has the attributes of x and has a local scope. The symbol y can then be declared with a weak scope using the .weak directive while keeping the other attributes of x.

```
x:
    y == x
    .weak y
```

Weak Scope Declaration for Windows NT (COFF32)

For Windows NT (COFF32), use the .weak directive in the following format to declare a symbol with a weak scope and search for defined symbols within other object files and libraries:

.weak identifier1 = identifier2

Where:

identifier1	Represents a symbol name that is assigned a weak symbol scope, which is resolved in link time.
identifier2	Represents a symbol name that holds the symbol definition.

Use the following syntax to declare a symbol with a weak scope and search for defined symbols within other object files and **not** within libraries:

.weak identifier1 == identifier2

Where:

identifier1	Represents a symbol name that is assigned a weak symbol scope, which is resolved in link time.
identifier2	Represents a symbol name that holds the symbol definition.

The following example illustrates a weak scope declaration where x: is a local defined symbol. x is the associated symbol for y. The .weak directive assigns y a weak scope.

x:
.weak y = x

Symbol Visibility Directives

A symbol's visibility, although it may be specified in an object file, defines how that symbol may be accessed once it has become part of an executable or shared object.

The default visibility of symbols is specified by the symbol's binding type. That is, global and weak symbols are visible outside of their defining component (executable file or shared object). Local symbols are hidden, as described below.

A symbol defined in the current executable file or shared object is protected if it is visible in other components but not preemptable. Preemptable means that any reference to such a symbol from within the defining component must be resolved to the definition in that component, even if there is a definition in another component.

A symbol defined in the current component is hidden if its name is not visible to other components. Such a symbol is necessarily protected. This directive may be used to control the external interface of a component.

To declare one or more symbols as protected, use the .protected directive. These symbols are flagged as protected symbols for the linkage editor. The .protected directive has the following format:

.protected name, name, ...

Where:

name	represents a symbol name.
Harric	represents a symbol name.

To declare one or more symbols as hidden, use the .hidden directive. These symbols are flagged as hidden symbols for the linkage editor. The .hidden directive has the following format:

.hidden name, name, ...

Where:

name	represents a symbol name.

To declare one or more symbols as exported, use the <code>.export</code> directive. These symbols are flagged as exported symbols for the linkage editor. The <code>.export</code> directive has the following format:

```
.export name, name, ...
```

name represents a symbol name.	
--------------------------------	--

Symbol Type Directive

The default type of a symbol in an object file is based on the assembly-time type of the symbol. See table <u>Symbol Types</u> below for a list of the symbol types and their predefined names. To explicitly specify a symbol's type, use the .type directive in the following format:

.type name, type

Where:

name	Represents a symbol name.
type	Specifies the symbol type using one of the predefined symbols listed in table Symbol Types that follows.

Symbol Types		
Symbol Types	Predefined Symbol Name of Type	
Symbolic constants and undefined symbols	@notype	
Labels and common symbols	@object	
Function names	@function	
Section names	Created by the assembler.	



The assembler automatically creates a symbol of type name for section names. When the object file format is COFF32 (Windows NT) the assembler creates a function symbol name for @function. For more information see the Procedure Label (PLabel) section.

Symbol Size Directive

To explicitly specify the size attribute of a symbol, use the .size directive. The .size directive has the following format:

.size name, size

Where:

name	Represents a symbol name.
size	Represents an absolute integer expression with no forward references.

To implicitly specify the default size attribute of a symbol, use a data allocation statement. The default symbol size is written to the symbol

table. See the **Data Allocation Statements** section for more information.



When the object file format is COFF32 (Windows NT), the .size directive is only effective for common symbols.

File Name Override Directive

By default, the file name is the name of the source file. To override the default file name use the .file directive. If you use the .file directive more than once in a source file, the assembler places multiple file names in the output object file. The .file directive has the following format:

.file "name"

Where:

name	Represents a string constant specifying a source file
	name.

Common Symbol Declarations

Common and local common symbol declarations enable you to define a symbol with the same name in different object files. The difference between a common symbol and local common symbol is as follows:

- The linker merges two or more common symbol declarations for the same symbol.
- The assembler merges two or more local common symbol declarations for the same symbol.

If a symbol is declared as both common and local common, the common declaration overrides the local common declaration. Any definition of a symbol supersedes either type of common declaration.

Common Symbol Directive

To declare a symbol as a common symbol, use the .common directive. Common symbols have a global scope, and do not necessarily have the same size and alignment attributes. The .common directive has the following format:

.common name, size, alignment

Where:

name	Represents a symbol name.	
size	Represents an absolute integer expression.	
alignment	Represents an absolute integer expression to the power of two. Not supported in COFF32 format.	



When the object file format is COFF32 (Windows NT), the alignment operand is not supported.

Local Common Symbol Directive

To declare a symbol as a local common symbol use the .lcomm directive. The .lcomm directive has the following format:

.lcomm name, size, alignment

Where:

name	Represents a symbol name.	
size	Represents an absolute integer expression.	
alignment	Represents an absolute integer expression to the power of two.	

The assembler allocates storage in the .bss or .sbss sections for undefined symbols declared as local common. The .bss or .sbss sections are chosen according to the size of the local common symbol. The assembler defines the symbol with the relocatable address of the allocated storage. The symbol is declared with a local scope, and assigned the largest size and alignment attributes of the local common declarations for that symbol.

Alias Declaration Directives

The .alias directive declares an alias for a label, a function name, or a symbolic constant. This directive can be used to reference an external symbol whose name is not legal in the assembly language. The .alias directive has the following format:

.alias symbol, "alias"

Where:

symbol	Represents a symbol name that the assembler can recognize. This name must be a valid name for the type of symbol.
"alias"	Represents a string constant, which is the name the assembler exports to the object file symbol table.

The .secalias directive declares an alias for a section name. This directive can be used to reference an external section whose name is not valid in the assembly language. The .secalias directive has the following format:

.secalias section-name, "alias"

section-name	Represents a section name that the assembler can recognize. This name must be a valid name for the type of section.
"alias"	Represents a string constant, which is the name the assembler exports to the object file symbol table.

Data Allocation

This section describes the Itanium(R) architecture assembly language statements used to allocate initialized and unitialized space for data objects in current sections and in cross sections, and to align data objects in sections of the code.

Data Allocation Statements

Data allocation statements allocate space for data objects in the current section, and initialize the space by assigning it a value. Data objects can be integer numbers, floating-point numbers, or strings. Integer numbers and floating point numbers are aligned according to their size. A data allocation statement with a <code>label</code>, defines a symbol of <code>@object</code> type, and sets the size attribute for that symbol.

Data allocation statements have any of the following formats:

[label:]	data1	expression,	
[label:]	data2	expression,	
[label:]	data4	expression,	
[label:]	data8	expression,	
[label:]	data16	expression,	
[label:]	real4	expression,	
[label:]	real8	expression,	
[label:]	real10	expression,	
[label:]	real16	expression,	
[label:]	string	"string",	
[label:]	stringz	"string",	

label	Specifies the data allocation address of the first data object.
expression	Represents any of the valid expression types listed in the Data Allocation Statements table, see below. Data alocation statements can have more than one epression operand.
string	Represents any of the valid string expression type values listed in the Data Allocation Statements table, see below.

The table below summarizes the data allocation mnemonics, and their expression type, memory format, data-object size, and alignment boundary for each.

	Data Allocation Statements			
Mnemonic	Expression Type	Memory Format	Size (in bytes)	Alignment
data1	Integer	Integer	1	1
data2	Integer	Integer	2	2
data4	Integer	Integer	4	4
data8	Integer	Integer	8	8
data16	Integer	Integer	16	16
real4	Floating point or Integer	IEEE single-precision floating point	4	4
real8	Floating point or Integer	IEEE double-precision floating point	8	8
real10	Floating point or Integer	IEEE extended- precision floating point (80-bit)	10	10
real16	Floating point or Integer	IEEE extended- precision floating point (80-bit)	16	16
string	String constant	Array of ASCII characters	Length of string	1
stringz	String constant	Array of ASCII characters with null terminator	Length of string + 1	1

To disable the automatic alignment of data objects in data allocation statements, add the .ua completer after the mnemonic, for example,

data4.ua. These statements allocate unaligned data objects at the current location within the current section.

The default byte order for data allocation statements is platform dependent. To specify the byte order for data allocation statements, use

the .msb, or .1sb directives described in the Byte Order Specification Directives section.

Uninitialized Space Allocation

The <code>.skip</code> and <code>.org</code> statements reserve uninitialized space in a section without assigning it a value. The <code>.skip</code> and <code>.org</code> statements enable the assembler to reserve space in any section type, including a <code>"nobits"</code> section. During program execution, the contents of a <code>"nobits"</code> section are initialized as zero by the operating system program loader. When using the <code>.skip</code> and <code>.org</code> statements in any other section type, the assembler initializes the reserved space with zeros.

The .skip statement reserves a block of space in the current section. The size of the block is specified in bytes, and is determined by an expression operand. The expression operand specifies the size of space reserved in the current section. The .skip statement with a label, defines a symbol of @object type, and sets the size attribute for that symbol.

The .skip statement has the following format:

[label:] .skip expression

Where:

label	Specifies the data allocation address of the beginning of the reserved block.
expression	Represents an absolute integer expression with no forward references. The location counter advances to a location relative to the current location within the section. This operand cannot have a negative value since the location counter cannot be reversed.

The .org statement reserves a block of space in the current section. The .org statement advances the location counter to the location specified by the expression operand. The .org statement with a label defines a symbol of @object type, and sets the size attribute for that symbol. The .org statement has the following format:

[label:] .org expression

label	Specifies the data allocation address of the beginning of the reserved block.
expression	Represents an integer, or a relocatable expression, with no forward references. If the expression is relocatable, it must be reducible to the form R+K, where R is a symbol previously defined in the current section, and K is an absolute constant. The location counter is set to the indicated offset relative to the beginning of the section. Since the location counter cannot be reversed, this operand must be greater than, or equal to, the current location counter.

Alignment

Instructions and data objects are aligned on natural alignment boundaries within a section. To disable automatic alignment of data objects in data

allocation statements, add the .ua completer after the data allocation mnemonic, for example, data4.ua. Bundles are aligned at 16-byte boundaries, and data objects are aligned according to their size. The assembler does not align string data, since they are byte arrays.

Each section has an alignment attribute, which is determined by the largest aligned object within the section.

Section location counters are not aligned automatically. To align the location counter in the current section to a specified alignment boundary use the <code>.align</code> statement. The <code>.align</code> statement has the following format:

.align expression

Where:

expression	Is an integer number that specifies the alignment boundary of the location counter in the current section. The integer must be
	a power of two.

The .align statement enables the assembler to reserve space in any section type, including a "nobits" section. During program execution time the contents of a "nobits" section are initialized as zero by the operating system program loader. When using the .align statement in any other section type, the assembler initializes the reserved space with zeros for non-executable sections, and with a NOP pattern for executable sections.



When the object file format is COFF32 (Windows NT) the section alignment boundary is limited to 8KB. The assembler does not guarantee alignment for requests above 8KB.

Cross-section Data Allocation Statements

Cross-section data allocation statements add data to a section that is not the current section. These statements save the overhead of switching between sections using the <code>.section</code> directive. See the Sections section for more information about switching between sections. Cross-section data allocation statements may be used within an explicit bundle. All data objects are aligned to their natural boundaries in the cross section. Cross-section data allocation statements have any of the following formats:

```
.xdata1 section, expression, ...
.xdata2 section, expression, ...
.xdata4 section, expression, ...
.xdata8 section, expression, ...
.xstring section, "string", ...
.xstringz section, "string", ...
```

Where:

section	Represents the name of a previously-defined section that is not the current section.
expression	Represents an absolute or relocatable integer expression. When these expressions reference a location counter, they refer to the location counter within the cross section, not within the current section.
string	Represents any of the valid string expression type values listed in the <u>Data Allocation Statements</u> table .

To disable automatic alignment of data objects in a cross-section data allocation statement, add the .ua completer to the statement, for example, .xdata4.ua. These statements allocate unaligned data objects at the current location counter of the cross section, not the current section.

The default byte order for cross-section data allocation statements is platform dependent. The byte order is determined by the cross section, not by the current section.

Miscellaneous Directives

This section describes the following Itanium(R) architecture assembly language directives:

- Register stack directive
- Rotating register directives
- Byte-order specification directive
- Ident string specification directive
- Radix indicator directive
- Preprocessor support

Register Stack Directive

The Itanium architecture provides a mechanism for register renaming. Register renaming is implemented by allocating a register stack frame consisting of input, local, and output registers. These registers can be renamed. These renamable registers map to the general registers r32 through r127. The assembler provides predefined alternate register names for the input, local, and output register areas of the register stack frame. The mapping of these registers to the general registers is determined by the nearest preceding alloc instruction.

Refer to the Intel(R) Itanium(R) Architecture Software Developer's Manual for detailed information about register renaming and for a full description of the alloc instruction.

The .regstk directive replaces the default register mappings defined by a preceding alloc instruction with new mappings. The .regstk directive

does not allocate a new register stack frame.

The .regstk directive has the following format:

```
.regstk ins, locals, outs, rotators
```

Where:

ins	Represents the number of input registers in the general register stack frame.
	0.
locals	Represents the number of local registers in the general register stack frame state.
	loc0 through loc $_{locals-1}$ represent r_{32+ins} through
	$r_{31+ins+locals}$ for locals > 0.
outs	Represents the number of output registers in the general register stack frame.
	out0 through out $_{outs-1}$ represent $r_{32+ins+locs}$ through
	$r_{31+ins+locals+outs}$ for outs > 0.
rotators	Represents the number of rotating registers in the general register frame. rotators must be <= ins+locals+outs.

The in, loc, and out register names defined by a previous .regstk directive or alloc instruction are visible by all subsequent instructions until the next .regstk directive or alloc instruction is specified.

The alternate register names specified by the operands of the <code>.regstk</code> directive refer to registers in the current register stack frame. If you reference input, local, or output registers using the alternate register names that are not within the current stack frame, the assembler produces an error message.

To prevent referencing the alternate register names, use the .regstk directive without the operands. The operands of a subsequent .regstk directive or alloc instruction redefine the mappings of the alternate register names.

The alloc instruction and .regstk directive do not affect the names of the general registers, r32 through r127.

Stacked Registers in Assignment and Equate Statements

To define an alternate register name for a stacked register, use an assignment statement. The alternate register name is not affected by any subsequent changes to the rotating register. See the Assignment Statements and Equate Statements sections for more details about assignment and equate statements.

Example Defining a Stacked Register in an Assignment Statement illustrates how to define an alternate register name using an assignment statement, so that the alternate register name is not affected by a subsequent .regstk directive. The local register name loc0 maps to the general register r36.loc0 is assigned to tmp. The subsequent add instruction refers to loc0, which is currently mapped to r40. The next add instruction refers to tmp which is mapped to r36, not r40.

Rotating Register Directives

General registers, floating-point registers, and predicate registers contain a subset of rotating registers. This subset of rotating registers can be renamed.

The following directives enable the programmer to provide names for one or more registers within each rotating register region:

- .rotr for general registers
- .rotf for floating-point registers
- .rotp for predicate registers

The .rotx directives assign alternate names and generation numbers for the rotating registers. One generation corresponds to one iteration of a software-pipelined loop. Each copied register is numbered with an index, where the most recent copy of a register has a zero index, such as b[0]. For every loop iteration, the registers within the group are renamed, and become one generation older by incrementing the index by one.

The .rotx directives define the number of instances of each pipeline variable and allocate them in the appropriate rotating register region. You can use an arbitrary name with a subscript-like notation for referencing the current and previous generations of each variable.

The rotating register directives have the following format:

```
.rotr name [expression], ...
.rotf name [expression], ...
.rotp name [expression], ...
```

Where:

name	Represents a register name specified by the user, and represents a pipelined variable.
expression	Specifies the number of generations needed for the variable. The expression must be an absolute integer expression with no forward references.

When the alias rotating register names are used as instruction operands, they have the following format:

```
name[expression]
```

name	Represents an alias rotating register name defined by one of the rotating register directives.
expression	Represents an absolute integer expression with no forward references. The index must be between 0 and $(n-1)$, where n is the number of generations defined for that name. If the index is negative, or greater than $(n-1)$, the assembler produces an error message.

The .rotr, .rotf, and .rotp directives cancel all previous alias names associated with the appropriate register file, before defining new register names. The register files include the general, floating-point, and predicate registers.

If the number of rotating general registers implied by a .rotr directive exceeds the number of rotating registers declared by the nearest preceding alloc instruction, or .regstk directive, the assembler issues a warning.

Using Rotating Register directives

Examples <u>Using the .rotp Directive</u> and <u>Using the .rotf Directive</u> illustrate the behaviour of the .rotp and .rotf directives, respectively.

Example <u>Using the .rotp Directive</u> illustrates how the .rotp directive declares alternate rotating predicate register names for two predicate registers, p[2], and three predicate registers q[3]. Instructions subsequent to the .rotp directive refer to p[0] for the current generation of p, and p[1] for the previous generation of p. For the current generation of p, the subsequent instructions refer to q[0], q[1] for the previous generation, and q[2] for the one before the previous generation.

```
Example: Using the .rotp Directive
.rotp p[2],q[3]

//The alternate predicate register names map to the predicate
//registers as follows:

p[0] = p16; p[1] = p17
q[0] = p18; q[1] = p19; q[2] = p20
```

Example <u>Using the .rotf Directive</u> illustrates how the .rotf directive declares alternate floating-point register names for three floating-point registers x[3], two floating-point registers y[2], and three floating-point registers z[3].

```
Example: Using the .rotf Directive .rotf \quad x[3], y[2], z[3] //The alternate floating-point register names map to the //floating-point registers as follows: x[0]=f32; x[1]=f33; x[2]=f34 y[0]=f35; y[1]=f36 z[0]=f37; z[1]=f38; z[2]=f39
```

Rotating Registers in Assignment and Equate Statements

To define an alias name for a rotating register, use an assignment statement. The alias register name is not affected by any subsequent changes to the rotating register. See the Assignment Statements and Equate Statements sections for more details about assignment and equate statements.

Example Defining an Alias Name in an Assignment Statement illustrates how to define an alias name using an assignment statement so that the alias name is not affected by a subsequent .rotr directive. The .rotr directive maps b[1] to general register r36. b[1] is assigned to tmp. The second .rotr directive defines the new mapping of b[1] to r33. The subsequent add instruction that refers to b[1] is currently mapped to r33. The second add instruction refers to tmp, which is mapped to r36, not r33.

Byte Order Specification Directives

The .msb and .1sb directives determine the byte order of data assembled by the datan, real n, and .xdatan data allocation statements. The values of n for data and .xdata are 1, 2, 4, and 8. The values of n for real are 4, 8, 10, and 16. See Data Allocation section for more information about data allocation statements.

The .msb and .lsb directives change the byte order for current sections only. They do not affect the instructions that are assembled. They only affect the data created. The default byte order is little-endian.

The .msb directive switches to MSB, where the most-significant byte is stored at the lowest address (big-endian). The .lsb directive switches to LSB, where the least-significant byte is stored at the lowest address (little-endian).

The byte order is a property of each section. If the byte order is changed in one section, it remains in effect for that section until the byte order is redefined. This change does not affect the byte order of other sections in the assembly program.

String Specification Directive

The .ident directive places a null terminated string in the .comment section of an output object file. See the use of .comment in Program Structure. The .ident directive has the following format:

```
.ident "string"
```

"string"	Represents a string.
----------	----------------------

Radix Indicator Directive

The .radix directive selects the numeric constant style.

To select a MASM numeric constant and specify a radix indicator, use the .radix directive in the following format:

.radix [radix-indicator]

Where:

radix-indicator	Indicates a MASM (Microsoft * macro assembler)
	numeric constant and specifies the radix. See table MASM Radix Indicators, for a list of the radix indicators.

The MASM numeric constant and radix remain in effect until redefined.

To select a C numeric constant, use the .radix directive in the following format:

.radix [C]

Where:

С	Indicates a C numeric constant.
---	---------------------------------

The .radix directive used with an operand, pushes the previous numeric constant style and radix onto a radix stack. The .radix directive without the radix-indicator operand, pops and restores the previous style and radix from the stack. The assembler may limit the depth of a radix stack, but this limit must be no less than 10 levels.

Preprocessor Support

The assembler recognizes a special filename and the line number directive (#line) inserted by the standard C preprocessor, and sets its

record as the current filename and line number accordingly. The #line directive has the following format:

#line line number, filename

Where:

line_number	Specifies the source line number
filename	Identifies the name of the current filename.

Additionally, the assembler supports the following built-in symbols:

@line Current line number

@filename Current filename

@filepath Current file path

Annotations

Annotations are a subset of the assembler directives. They explicitly provide additional information for the assembler during the assembly process. These annotations have the same format and syntax as all other directives. This section describes these annotations and their functionality. The annotations covered in this section include:

- .pred.rel
- .pred.vector
- .mem.offset
- .entry

Predicate Relationship Annotation

The predicate relationship annotation .pred.rel provides information for the assembler about a logical relationship between the values of predicate registers. It is relevant only for explicit code.

The annotation .pred.rel takes the following forms:

"mutex" mutual exclusion

"imply" implication

"clear" clear existing relations

When conflicting instructions follow an entry point, IAS ignores all existing predicate relationships defined before the entry point.

Predicate Vector Annotation

The predicate vector annotation .pred.vector explicitly specifies the predicate register contents using a user-defined value. The user-defined value is represented by a 64-bit binary number and each bit corresponds to a predicate register, respectively. A second optional operand can be used as a mask to selectively set only some of the predicate registers. Currently this annotation is ignored by the Intel(R) Itanium(R) Assembler.

This annotation takes effect at the point of insertion and the assembler may use this information for further analysis. The .pred.vector annotation has the following syntax:

```
.pred.vector val [, mask]
```

Where:

val	Specifies a number represented as a 64-bit binary number. Each bit represents a 1-bit value in each of the corresponding 64 predicate registers. If val is not within the 64-bit range, this annotation is ignored.
mask	Represents an optional mask value used to define a subset of the predicate register file.

Example <u>Using a Predicate Vector Annotation with a Mask</u> illustrates a predicate vector annotation that sets the predicate registers according to the specified value 0x9, and uses a mask of 0xffff to define a subset of the predicate register file.

Memory Offset Annotation

The memory offset annotation .mem.offset provides hints about the address that memory operations address, when the exact address is unknown. The annotation is useful for avoiding false reports of dependency violations. The annotation affects the instruction that follows.

The .mem.offset annotation has the following syntax:

```
.mem.offset off val,base ind
```

Where:

off_val	The relative offset for the memory region where the data is stored or retrieved.
base_ind	A number that identifies the memory region where the
	information is stored or retrieved. The number is an
	arbitrary method of distinguishing between different
	memory regions.

Example Using the Memory Offset Annotation illustrates a .mem.offset annotation.

```
Example: Using the Memory Offset Annotation
.proc foo
foo::
FOO STACK INDEX=0
                                //code...
.mem.offset 0,FOO STACK INDEX //Suppose r3 contains the stack pointer
st8.spill [r3]=r32,8
                                //We want to save r32-r34
.mem.offset 8,FOO STACK INDEX
st8.spill [r3]=r33,8
.mem.offset 16,FOO STACK INDEX
st8.spill [r3]=r34,8
.endp
.proc bar
bar::
.BAR STACK INDEX=1
.mem.offset 0,BAR STACK INDEX //Suppose r3 contains the stack pointer
st8.spill [r3]=r40
                                //We want to save r40
```

Entry Annotation

The entry annotation <code>.entry</code> notifies the assembler that a label can be entered from another function. By default, only global labels, designated by

<label>::, are considered entry points. The annotation and the label need not be consecutive.

The .entry annotation has the following syntax:

```
.entry label [, labels...]
```

16	abel	Represents the associated label.

Example: Using the Entry Annotation		
.entry A	//entry annotation	
A: mov r1=r2		

Register Names by Type

This section contains eight tables that list the following the Itanium(R) architecture registers and their names:

- · General Registers
- Floating-point Registers
- Predicate Registers
- Branch Registers
- Application Registers
- Control Registers
- Other Registers
- Indirect-register Files

General Registers

Register	Register Name	
Fixed general registers	r0 - r31	
Stacked general registers	r32 - r127	
Alternate names for input registers	in0 - in95	
Alternate names for local registers	10c0 - 10c95	
Alternate names for output registers	out0 - out95	
Global pointer (r1)	gp	
Return value registers (r8-r11)	ret0 - ret3	
Stack pointer (r12)	sp	

Floating-point Registers

Register	Register Name	
Floating-point registers	f0 - f127	
Argument registers (f8-f15)	fret0 - fret7	
Return value registers (f8-f15)	fret0 - fret7	

Predicate Registers

Register	Register
Predicates	p0 - p63
All predicates	pr
Rotating predicates	pr.rot

Branch Registers

Register	Register Name	
Branch registers	b0 - b7	
Return pointer (b0)	rp	

Application Registers

Register	Register Number	Register Name
Application registers by number	0 - 127	ar0 - ar127
Kernel registers	0 - 7	ar.k0 - ar.k7
RSE control register	16	ar.rsc
Backing store pointer	17	ar.bsp
Backing store "store" pointer	18	ar.bspstore
RSE NaT collection register	19	ar.rnat
Compare & Exchange comparison value	32	ar.ccv
User NaT collection register	36	ar.unat
Floating-point status register	40	ar.fpsr
Interval time counter	44	ar.itc
Previous frame state	64	ar.pfs
Loop counter	65	ar.lc
Epilog counter 66	66	ar.ec

Control Registers

Register	Register Number	Register Name
Control registers by number	0 - 127	cr0 - cr127
Default control register	0	cr.dcr
Interval time match 1	1	cr.itm
Interruption vector address 2	2	cr.iva
Page table address 8	8	cr.pta
Interruption processor status register	16	cr.ipsr
Interruption status register	17	cr.isr
Interruption data address	18	cr.ida
Interruption instruction pointe	19	cr.iip
Interruption data translation register	20	cr.idtr
Interruption instruction translation register	21	cr.iitr
Interruption instruction previous address	22	cr.iipa
Interruption frame state	23	cr.ifs
Interruption immediat	24	cr.iim
Interruption hash address	25	cr.iha
External interrupt registers	66	cr.lid
	71	cr.ivr
	72	cr.tpr
	75	cr.eoi
	96,98,100,102	cr.irr0 - cr.irr3
	114	cr.itv
	116	cr.pmv
	117 - 118	cr.lrr0 - cr.lrr1
	119	cr.cmcv

Other Registers

Register	Register Name
Processor status register	psr
Processor status register, lower 32 bits	psr.l
User mask psr.um	psr.um
Instruction pointer	ip

Indirect-register Files

Register	Register Name
Performance monitor control registers	pmc[r]
Performance monitor data registers	pmd[r]
Protection key registers	pkr[r]
Region registers	rr[r]
Instruction breakpoint registers	ibr[r]
Data breakpoint registers	dbr[r]
Instruction translation registers	itr[r]
Data translation registers	dtr[r]
Processor identification register	CPUID[r]

Pseudo-ops

This section contains two tables of pseeudo-ops:

- Pseudo-ops Listed by Opcode
- Pseudo-ops with Missing Operands

Pseudo-ops Listed by Opcode

The table that follows lists the assembly language pseudo-ops for the Itanium(R) architecture according to their opcodes. The table lists pseudo-ops with missing operands. The opcodes are listed alphabetically, with their operands, and the equivalent machine instructions. The table lists mnemonics converted to other mnemonics.

Opcode	Instruction Description	Operands	Equivalent Machine Instruction
add	Add immediate	r1 =imm,r3	adds $r1 = imm14, r3$
			addl $r1 = imm22, r3$
break	Break	imm21	break.b imm21 (B)
			break.i imm21 (I)
			break.m imm21 (M)
			break.f imm21 (F)
chk.s	Speculation check	r2,target25	chk.s.i r2,target25(I)
			11
fabs	Floating-point	f1 =f3	chk.s.m $r2$, $target25$ (M) fmerge.s $f1 = f0$, $f3$
Labs	Floating-point		Interge.s II -10,13
	absolute value		
fadd.pc.sf	Floating-point add	f1 =f3,f2	fma.pc.sf f1 =f3,f1,f2
fcvt.xuf	Convert integer to float	f1 =f3	fma.pc.sf f1 =f3,f1,f0
	unsigned		
fmpy.pc.sf	Floating-point	f1 =f3,f4	fma.pc.sf $f1 = f3, f4, f0$
	Trodaing point	11 10,11	
	multiply		
fneg	Floating-point	f1 =f3	fmerge.ns $f1 = f3, f3$
	negate		
fnegabs	Floating-point	f1 =f3	fmerge.ns $f1 = f0, f3$
	negate absolute		
	value		
fnorm.pc.sf	Floating-point	f1 =f3	fma.pc.sf f1 =f3,f1,f0
C 1 C	normalize	C1 C2 C0	5 5 51 52 51 50
fsub.pc.sf	Floating-point	f1 =f3,f2	fms.pc.sf $f1 = f3, f1, f2$
	subtract		
ld8.mov	1d8 that can be	r2=[r3],	ld8 r2=[r3]
	translated to mov. It is		
	used to support link time rewriting of indirect	Symbol+Addend	mov <i>r2=r3</i>
	addressing code		
	sequences. In ELF		
mov	format only. Move to application	ar3 =imm8	mov.i ar3 =imm8 (I)
			, , , , , , , , , , , , , , , , , , ,

]	register	1	mov.m ar3 =imm8 (M)
	1 og.stol		
	immediate		
mov	Move to application register	ar3 =r2	mov.i $ar3 = r2$ (I)
			mov.m $ar3 = r2$ (M)
mov	Move	f1 =f3	fmerge.s $f1 = f3, f3$
	floating-point		
	register		
mov	Move from application register	r1 =ar3	mov.i $r1 = ar3 (I)$
			mov.m $r1 = ar3 (M)$
mov	Move immediate	r1 =imm22	addl $r1 = imm22, r0$
mov	Move general	r1 =r2	adds $r1 = 0, r2$
	register		
mov	Move to branch	b1 =r2	mov $b1 = r2$
	register		
nop	No operation	imm21	nop.b
			nop.i imm21 (I)
			nop.m imm21 (M)
			nop.f imm21 (F)
shl	Shift left	r1=r2,count6	dep.z r1=r2,count6, 64-count6
shr	Shift right signed	r1=r3,count6	extr r1=r3,count6, 64-count6
shr.u	Shift right unsigned	r1=r3,count6	extr.u r1=r3,count6, 64-count6
xma.lu	Fixed-point	f1=f2,f3,f4,	xma.l $f1 = f2, f3, f4$
	multiply low		
	unsigned		

Pseudo-ops with Missing Operands

The table below lists pseudo-ops that omit one or more operands of the machine instruction. The assembler substitutes the missing operand with a predefined value. The missing operand(s) appear as bold text. In addition to omitting many operands, many completers may also be omitted.

Pseudo-op	Missing Operand(s)		Substitute Value
alloc	alloc	r1=ar.pfs,i,l,o,r	ar.pfs
cmp	cmp.crel.ctype	p1,p2=imm8,r3	р0
cmp	cmp.crel.ctype	p1,p2=r2,r3	р0
cmp4	cmp4.crel.ctype	p1,p2=imm8,r	р0
cmp4	cmp4.crel.ctype	p1,p2=r2,r3	р0
cmpxchg	cmpxchgsz.sem.ldhir	nt r1=[r3],r2,ar.ccv	ar.ccv
fclass	fclass.m.fctype	p1,p2=f2,f3	p0
	fclass.nm.fctype	p1,p2=f2,f3	
fcmp	fcmp.fcrel.fctype.s	sf p1,p2=f2,f3	р0
mov	mov pr=r2,mask17		all ones
tbit	tbit.trel.ctype	p1,p2=r3,pos6	р0
tnat	tbit.trel.ctype	p1,p2=r3	p0

Link-relocation Operators

The table below lists and describes the link-relocation operators and their usage. Unless otherwise specified, the usage is for both COFF and ELF formats.

Operator	Generates a Relocation For:	Usage
@dtpmod(expr)	The current instruction requests the linker to put the load module index for expr. It is used in dynamically-bound programs.	data8 statement in ELF format .
@dtprel(expr)	The current instruction or data object that calculates the static dtv-relative offset to the address given by <code>expr</code> . It is used in dynamically-bound programs.	The adds, addl, and movl instructions and data8 statement in ELF format.
@gprel(expr)	The current instruction or data object that calculates the gp-relative offset to the address given by <code>expr</code> .	The addl instruction, and data8 (and data4 in ELF format) statements.
@ltoff(expr)	The current instruction that instructs the linker to create a linkage table entry for $expr$, and calculates the gprelative offset to the new linkage table entry.	add long immediate instructions.
<pre>@ltoff(@dtpmod (expr))</pre>	The current instruction requests the linker to allocate a linkage table entry to hold the load module index for <code>expr</code> . The linker processes this relocation by substituting the <code>gp</code> -relative offset for the new linkage table entry. It is used in dynamically- bound programs.	The add long immediate instruction in ELF format.
<pre>@ltoff(@dtprel (expr))</pre>	The current instruction that instructs the linker to create a linkage table entry to hold the dtv-relative offset for expr and calculates the gp-relative offset to the new linkage table entry. It is used in dynamically-bound programs.	The add long immediate instruction in ELF format.
<pre>@ltoff(@tprel (expr))</pre>	The current instruction that instructs the linker to create a linkage table entry to hold the tp -relative offset for $expr$, and calculates the gp -relative offset to the new linkage table entry. It is used in statically-bound programs.	The add long immediate instruction in ELF format.
@ltoffx(expr)	The current instruction that instructs the linker to create a linkage table entry for <code>expr</code> , and calculates the <code>gp-relative</code> offset to the new linkage table entry. It is used to support link-time rewriting of the indirect addressing code sequences.	The add long immediate instruction in ELF format.
@secrel (expr)	The current data object that calculates the offset, relative to the beginning of the section, to the address given by $expx$.	data4 and data8 statements, and the addl instruction.
@segrel(expr)	The current data object that calculates the offset, relative to the beginning of the segment, to the address given by <code>expr</code> .	data4 and data8 statements, in ELF format.
@imagerel(expr)	The current data object that calculates the offset, relative to the beginning of the image, to the address given by <code>expr</code> .	data4 statements, in COFF format.
@fptr(sym)	The current instruction or data object that calculates the address of the official <code>plabel</code> descriptor for the symbol <code>sym</code> , which must be a procedure label (function descriptor) name.	data4 and data8 statements, and move long immediate instructions. Requires function symbol in COFF format. It can be used in add long immediate instructions when combined with the @ltoff operator in the

		@ltoff(@fptr(sym)
@pltoff(sym)	The current instruction or data object that calculates the gp-relative offset to the procedure linkage table entry for the symbol sym, which must be a function name.	form. data8 statements and add long immediate instructions. The PLT entry referenced by this operator should be used only for a direct procedure call. It does not serve as a function descriptor name.
@iplt(sym)	The current data object that calculates the <code>plabel</code> descriptor for the symbol <code>sym</code> , which must be a procedure label (function descriptor) name.	data16 statements in ELF format.
@ltv(expr)	The current data object that calculates the address of the relocatable expression <code>expr</code> , with one exception; while it is expected that the addresses created will need further relocation at run-time, the linker should not create a corresponding relocation in the output executable or shared object file. The run-time consumer of the information provided is expected to relocate these values.	data4 statements in ELF format .
@section(sec)	The current data object that provides the section header number of section sec. Used for debug information.	data2 statements in COFF format.
@tprel(expr)	The current instruction or data object that calculates the tp-relative offset to the address given by <code>expr</code> . It is used in statically-bound programs.	The adds, addl, and movl instructions and data8 statement in ELF format.

List of Assembly Language Directives

The table below summarizes the Itanium(R) architecture assembly language directives by category.

Category	Directive
Alias declaration directives	.alias
	.secalias
Assembler annotations	.pred.rel
	.pred.vector
	.mem.offset
	· mem · Offset
	.entry
Assembler modes	.auto
	.explicit
	.default
Byte order specification directive	.msb
	.1sb
Common symbol declaration directives	
Common symbol declaration directives	.common
	.lcomm
Cross-section data allocation statements	.xdata1
	.xdata2
	.xdata4
	.xdata8
	.xstring
	. ASCITING
	.xstringz
Data-allocation statements data1	data1
	data2
	data4
	da + a 0
	data8
	real4
	real8
	real10
	real16

	string
	stringz
Explicit template selection directives	.mii
	.mfi
	• • • • • • • • • • • • • • • • • • • •
	.bbb
	.mlx
	.mib
	.mmb
	.mmi
	.mbb
	.mfb
	.mmf
File symbol declaration directive	.file
Ident string directive	.ident
Include file directive	.include
Language specific data directive (Windows*-specific)	.handlerdata
Procedure declaration directives	.proc
	on dn
Radix indicator directive	.endp
Register stack directive	.regstk
Reserving uniniatialized space statements	.skip
Reserving unimationized space statements	.svib
	.org
Rotating register directives	.rotr
	.rotp
	.rotf
Section directives	.section
	.pushsection
	.popsection
	.previous
	.text
	.data
	.sdata

	.bss
	.sbss
	.rodata
	.comment
Section and data alignment directive	.align
Stack unwind information directives	See Stack Unwind Directives table
Symbol scope declaration directives	.global
	.weak
	.local
Symbol visibility directives	.protected
	.hidden
	.export
Symbol type and size directives	.type
	.size
Symbolic debug directive	.ln
Symbolic debug directive Windows-specific	.bf
Virtual register allegation directives	.ef
Virtual register allocation directives	.vreg.allocatable
	.vreg.safe_across_calls
	.vreg.family
	.vreg.var
	.vreg.undef

Glossary

A virtual (not physical) address within the process' address space that is computed as an
process' address space that is computed as an
absolute number.
An expression that is not subject to link-time
relocation.
Two identifiers referring to the same element.
A program that translates assembly language
into machine language.
A low level symbolic language closely resembling machine-code language.
The process of resolving a symbolic reference
in one module by finding the definition of the
symbol in another module, and substituting the address of the definition in place of the
symbolic reference. The linker binds relocatable object modules together, and the
DLL loader binds executable load modules.
When searching for a definition, the linker and
DLL loader search each module in a certain
order, so that a definition of a symbol in one
module has precedence over a definition of the same symbol in a later module. This order is called the binding order.
128 bits that include three instructions and a
template field.
Common Object File Format, an object-module
format.
An assembler instruction that does not produce executable code.
The time during which a program is actually
executing, not including the time during which
the program and its DLLs are being loaded.
A sequence of symbols that represents a value.
A label that refers to a procedure entry point.
Symbol visible outside the source file in which
it is defined.

IA-32	Intel Architecture-32: the name for Intel's
	current 32-bit Instruction Set Architecture
	(ISA).
identifier	Syntactic representation of symbol names using
i de i i di i	alphabetic or special characters, and digits.
instruction	An operation code that performs a specific machine operation.
instruction group	Itanium(R) architecture instructions are organized in instruction groups. Each instruction group contains one or more statically contiguous instructions that execute in parallel. An instruction group must contain at least one instruction; there is no upper limit on the number of instructions in an instruction group.
	An instruction group is terminated statically by
	a stop, and dynamically by taken branches.
	Stops are represented by a double semi-colon
	(;;). You can explicitly define stops. Stops immediately follow an instruction, or appear on a separate line. They can be inserted between two instructions on the same line, as a semi-colon (;) is used to separate two instructions.
Instruction Set	The architecture that defines application level
Architecture	resources which include: user-level instructions, addressing modes, segmentation,
	and user visible register files. instruction tag A label that refers to an instruction.
ISA	See Instruction Set Architecture
Itanium processor	Name of Intel's first 64-bit processor.
label	A location in memory of code or data.
link time	The time when a program, dynamic-link library (DLL), or starred object is processed by the linker. Any activity taking place at link time is static.
linkage table	A table containing text, unwind information, constants, literals, and pointers to imported data symbols and functions.
local symbol	Symbol visible only within the source file in
	which it is defined.
location counter	Keeps track of the current address when assembling a program. It starts at zero at the beginning of each segment and increments appropriately as each instruction is assembled. To adjust the location counter of a section, use the .align directive, or the .org directive.
memory stack	A contiguous array of memory locations, commonly
	referred to as "the stack", used in many processors to

	save the state of the calling procedure, pass parameters to the called procedure and store local variables for the currently executing procedure.
mnemonic	A predefined assembly-language name for
	machine instructions, pseudo-ops, directives,
	and data-allocation statements.
multiway branch bundle	A bundle that contains more than one branch
	instruction.
name space	A virtual (not physical) file. The assembler assigns names to a symbol, register, or mnemonic name space. Usually a name is defined only once in each separate name space. A name can be defined twice, in the symbol and register name space. In this case the register name takes precedence over the symbol name.
operator	The assembly-language operators indicate
	arithmetic or bitwise-logic calculations.
plabel	See procedure label.
predicate registers	64 1-bit predicate registers that control the execution of instructions. The first register, p0, is always treated as 1.
predication	The conditional execution of an instruction
	used to remove branches from code.
procedure label	A reference or pointer to a procedure. A procedure label (PLabel) is a special descriptor that uniquely identifies the procedure. The PLabel descriptor contains the address of the function's actual entry point, and the linkage table pointer.
pseudo-op	An instruction aliasing a machine instruction,
	provided for the convenience of the
	programmer.
qualifying predicate	The execution of most instructions is gated by a qualifying predicate. If the predicate is true, the instruction executes normally; if the instruction is false the instruction does not modify architectural state or affect program behaviour.
register rotation	Software renaming of registers to provide every loop iteration with its own set of registers.
register stack configuration	A 64-bit register used to control the register
	stack engine (RSE).
relocatable expression	An expression that is subject to link-time
	relocation
rotating registers	Registers which are rotated by one register
	position at each loop execution so that the
	content of register X is in register X+1 after one rotation. The predicate, floating-point, and general registers can be rotated. The registers are rotated in a wrap-around fashion.

section	Portions of an object file, such as code or data, bound to one unit.
software pipelining	Pipelining of a loop by way of allowing the
	processor to execute, in any given time, several instructions in various instructions of the loop.
stacked registers	Stacked general registers, starting at r32, used
	to pass parameters to the called procedure and store local variables for the currently executing procedure.
statement	An assembly-language program consists of a
	series of statements. The following are primary
	types of assembly-language statements:
	label statements
	instruction statements
	directive statements
	assignment statements
	equate statements
	data allocation statements
	cross-data allocation statements
stop	Indicates the boundary of an instruction group. It is placed in the code by the assembly writer or compiler.
symbol declaration	The symbol address is resolved, not necessarily based on the current module. Declare symbols using a .global or .weak directive.
symbol definition	The symbol address is resolved based on the
	current module. A symbol is defined by assigning it a type and value. You can define a
	symbol either in an assignment statement, by
	using it as a label, or with a .common directive.
temporary symbol	A symbol name that is not placed in the
	object-file symbol table. To define a temporary symbol name, precede the name with a period (.).
weak symbol	Undefined symbol in object file, resolved
	during link time.